

# Span-program-based quantum query algorithms

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Ratnieki, 2014. gada 3. oktobris



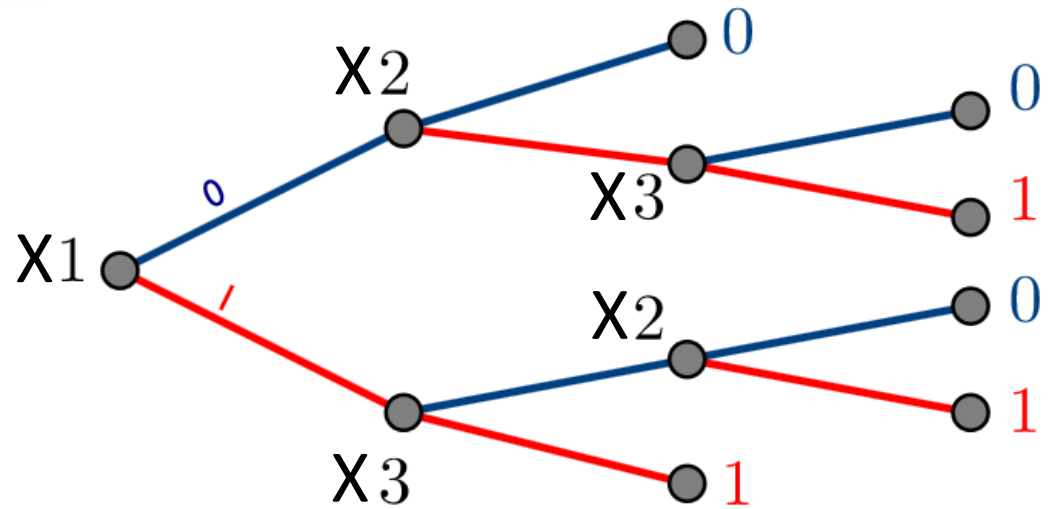
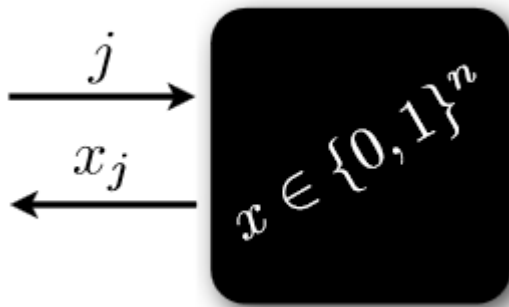
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# History of span programs

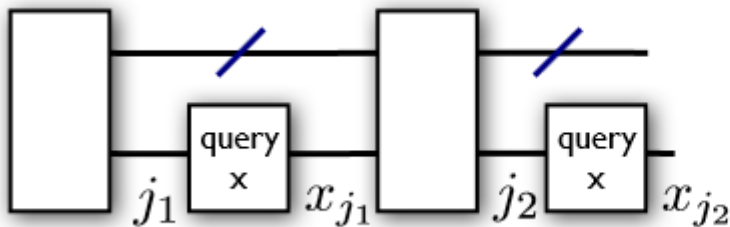
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- ❑ First defined in 1993 by Karchmer, Wigderson
- ❑ Rediscovered in 2007, used for evaluating Boolean formulas by Reichardt, Špalek
- ❑ In 2010 Reichardt proved that span programs are equivalent to quantum query algorithms
- ❑ Used for s-t connectivity, triangle finding, k-distinctness, graph collision, ...
- ❑ Basis for Belovs's *Learning Graph* approach

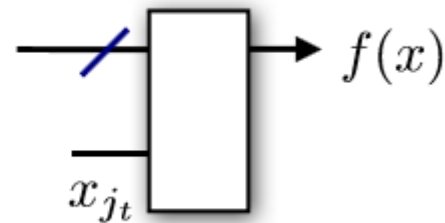
# Decision tree model



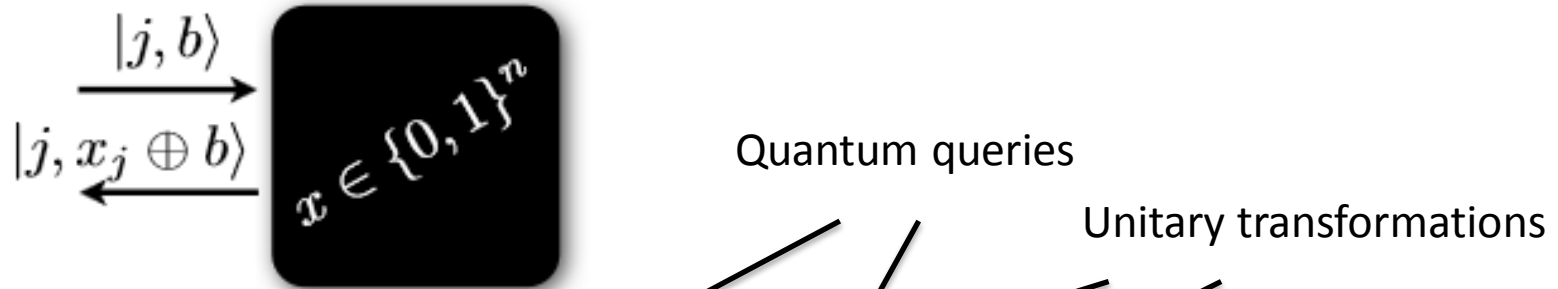
$\Rightarrow \text{MAJ}(x_1, x_2, x_3)$



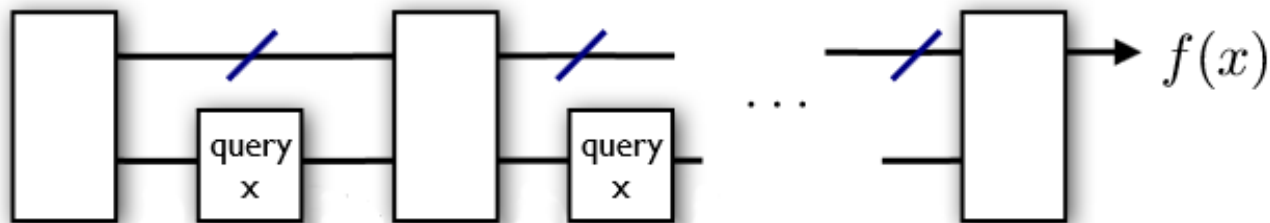
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# Quantum query model



$$|x\rangle_I |\psi_x^t\rangle_A = U_t O U_{t-1} \dots U_1 O U_0 |x\rangle_I |1, 0\rangle_Q |0\rangle_W$$



# Notation

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$$\square \text{Span}(S) = \left\{ \sum_{i=1}^k \lambda_i v_i \mid k \in \mathbb{N}, v_i \in S, \lambda_i \in \mathbb{F} \right\}$$

$$\square \text{Bra: } \langle u | = (c_1, c_2, \dots, c_n) \quad \text{Ket: } |v\rangle = \begin{pmatrix} a_1 \\ a_2 \\ \dots \\ a_n \end{pmatrix}$$

□ Inner product:

$$\langle u | v \rangle = a_1 c_1 + a_2 c_2 + \dots + a_n c_n$$

$$\square \text{Norm: } \|v\| = \sqrt{a_1^2 + a_2^2 + \dots + a_n^2}$$

# Span program $P$ on $n$ bits

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Vector space:  $V$

Target vector:  $|t\rangle$

Sets of vectors:  $V_{1,0}, V_{1,1}, \dots, V_{n,0}, V_{n,1}, V_{free}$

If  $x_i = b$  then vectors  $V_{i,b}$  are available

$P$  «computes»  $f_P : \{0,1\}^n \rightarrow \{0,1\}$

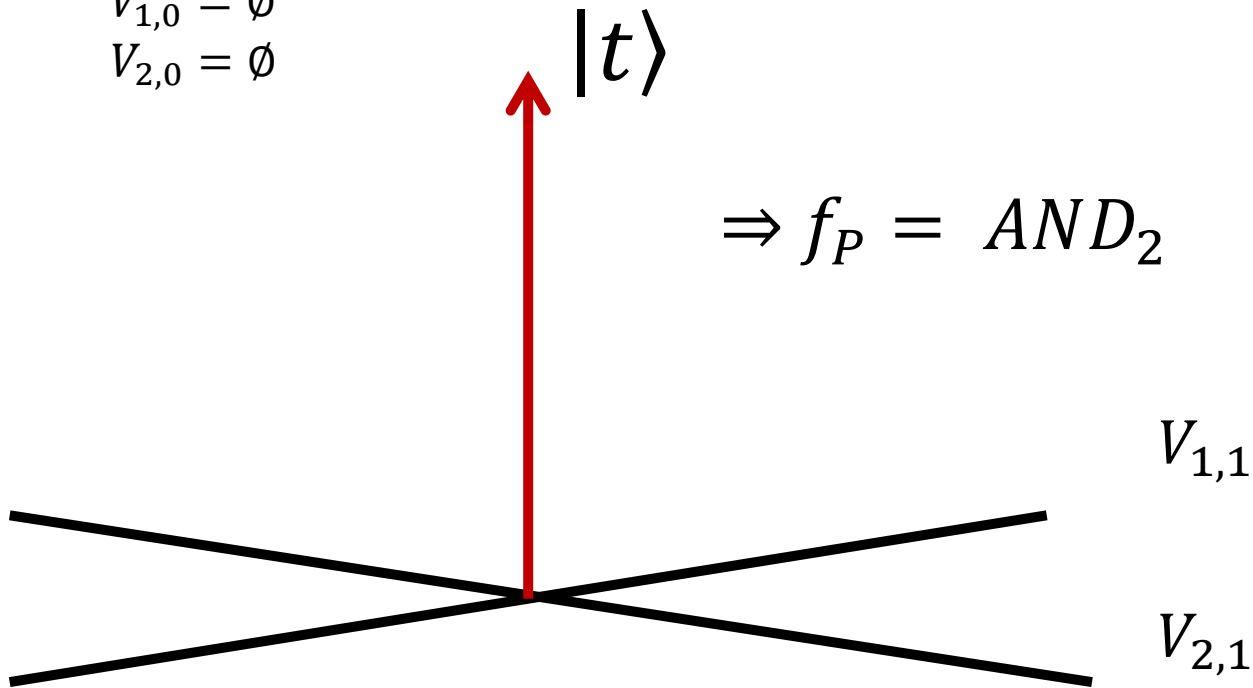
$$f_P(x) = 1 \iff |t\rangle \in \text{Span} \left( V_{free} \cup \bigcup_j V_{j,x_j} \right)$$

# Span program for «AND» function

Geometric example:  $V = \mathbb{R}^2$

$$V_{1,0} = \emptyset$$

$$V_{2,0} = \emptyset$$



# Span program for «XOR» function

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- $f(x_1, x_2) = x_1 \oplus x_2$
- Pick the target vector:  $|t\rangle = \begin{pmatrix} 1 \\ 1 \end{pmatrix}$ 
  - if  $x_1 = 1$  then make available the vector  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$
  - if  $x_1 = 0$  then make available the vector  $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$
  - if  $x_2 = 1$  then make available the vector  $\begin{pmatrix} 1 \\ 0 \end{pmatrix}$
  - if  $x_2 = 0$  then make available the vector  $\begin{pmatrix} 0 \\ 1 \end{pmatrix}$



# Span program for «XOR» function

---

- $f(x_1, x_2) = x_1 \oplus x_2$
- Vector space:  $V = \mathbb{R}^2$
- Basis vectors:  $\{|0\rangle, |1\rangle\}$
- Pick the target vector:  $|t\rangle = |0\rangle + |1\rangle$ 
  - $x_1 = 1 : \{|0\rangle\}$
  - $x_1 = 0 : \{|1\rangle\}$
  - $x_2 = 1 : \{|0\rangle\}$
  - $x_2 = 0 : \{|1\rangle\}$

# Span program for « $OR_n$ » function

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- $f(x_1, x_2, \dots, x_n) = x_1 \vee x_2 \vee \dots \vee x_n$
- Vector space:  $V = \mathbb{R}$
- Basis vectors:  $\{|0\rangle\}$
- Pick the target vector:  $|t\rangle = |0\rangle$
- For every  $i \in [1..n]$ :
  - $x_i = 1 : \{|0\rangle\}$
  - $x_i = 0 : \{\}$

# Case $f_P(x) = 1$ : positive witness

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- $A$  – column matrix of the available vectors
- $|w\rangle$  - the positive witness
- $wsize_1(P, x) = \min_{|w\rangle: A|w\rangle=|t\rangle} \||w\rangle\|^2$
- $wsize_1(P, x)$  – essentially a sum of squared coefficients for those vectors that are used to express the target vector
- $wsize_1(P) = \max_{x \in \{0,1\}^n} wsize_1(P, x)$

# « $OR_n$ »: positive witness

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- Target vector:  $|t\rangle = |0\rangle$
- For every  $i \in [1..n]$ :
  - $x_i = 1 : \{ |0\rangle \}$
  - $x_i = 0 : \{ \}$
- If for some  $x_i = 1$  then the target vector can be expressed:  $|t\rangle = 1 * |0\rangle$
- $wsize_1(P) \leq 1^2$

# Case $f_P(x) = 0$ : negative witness

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- $V(x) = V_{free} \cup \bigcup_{j \in [1..n]} V_{j, x_j}$
- $V(\neg x) = V_{free} \cup \bigcup_{j \in [1..n]} V_{j, (1-x_j)}$
- $|w'\rangle$  - the negative witness
- Need to find such  $|w'\rangle$  that  $\langle w'|t\rangle = 1$  and  $\forall |y\rangle \in V(x) \ (|w'\rangle \perp |y\rangle)$
- $wsiz_0(P, x) = \min_{|w'\rangle} \sum_{|y\rangle \in V(\neg x)} \langle w'|y\rangle^2$
- $wsiz_0(P) = \max_{x \in \{0,1\}^n} wsiz_0(P, x)$

# « $OR_n$ »: negative witness

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- Target vector:  $|t\rangle = |0\rangle$
- For every  $i \in [1..n]$ :
  - $x_i = 1 : \{ |0\rangle \}$
  - $x_i = 0 : \{ \}$
- If all  $x_i$  are equal to 0 then can take negative witness:  $|w'\rangle = |0\rangle$
- $wsize_0(P) \leq 1^2 + 1^2 + \dots + 1^2 = n$

# Span program complexity

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- $wsiz(P) = \sqrt{wsiz_1(P) * wsiz_0(P)}$
- $Q(f)$  - quantum query complexity
- $Q(f) = O(wsiz(P_f))$
- For « $OR_n$ »:  
$$wsiz(P) = \sqrt{1 * n} = \sqrt{n}$$

# Span program for « $OR_n$ » function

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- If  $m = \#i: (x_i = 1)$  then the target vector can be expressed:  $|t\rangle = \frac{1}{m} |0\rangle + \frac{1}{m} |0\rangle + \dots + \frac{1}{m} |0\rangle$
- $wsize_1(P) \leq m \left(\frac{1}{m}\right)^2 = \frac{1}{m}$
- $wsize_0(P) \leq 1^2 + 1^2 + \dots + 1^2 = n$
- $wsize(P) = \sqrt{wsize_1(P) * wsize_0(P)} = \sqrt{\frac{n}{m}}$



# Graph bipartiteness

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- $n$  – number of vertices in the given graph
- We will construct an  $\theta(n\sqrt{n})$  algorithm for testing if the given graph is bipartite
- It's asymptotically optimal
- Any classical algorithm would need to consider all edges – in worst case  $\Omega(n^2)$  queries
- Main idea: look for an odd cycle
- An undirected graph is bipartite iff it has no odd cycles

# Graph bipartiteness

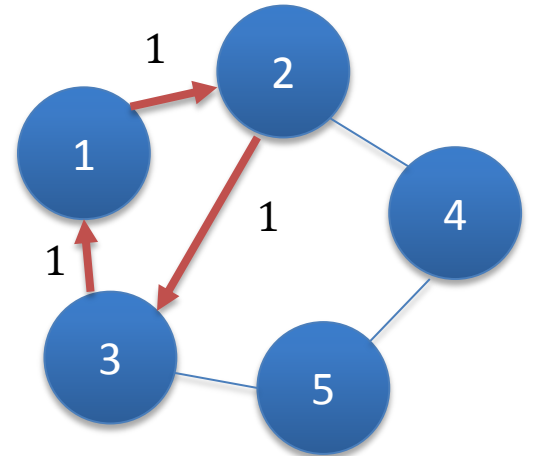
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- Vector space:  $V = \mathbb{R}^{2n^2+1}$
  - Basis vectors:  $\{|0\rangle\} \cup \{|v_{k,b}\rangle | v, k \in [1..n], b \in \{0,1\}\}$
  - Target vector:  $|t\rangle = |0\rangle$
  - For every  $k \in [1..n]$ : can use the free vector  $|0\rangle + |k_{k,0}\rangle + |k_{k,1}\rangle$
  - For every  $k \in [1..n]$ :
    - for every edge  $u - v$  (where input  $x_{u,v} = 1$ ) make available the vectors:  
 $|u_{k,0}\rangle + |v_{k,1}\rangle$  and  $|u_{k,1}\rangle + |v_{k,0}\rangle$
-

# Graph bipartiteness

$$|t\rangle = (|0\rangle + |1_{1,0}\rangle + |1_{1,1}\rangle) - (|1_{1,0}\rangle + |2_{1,1}\rangle) \\ + (|2_{1,1}\rangle + |3_{1,0}\rangle) - (|3_{1,0}\rangle + |1_{1,1}\rangle)$$

$$wsize_1(P, x) \leq 1^2 + (-1)^2 + 1^2 + (-1)^2 = 4$$

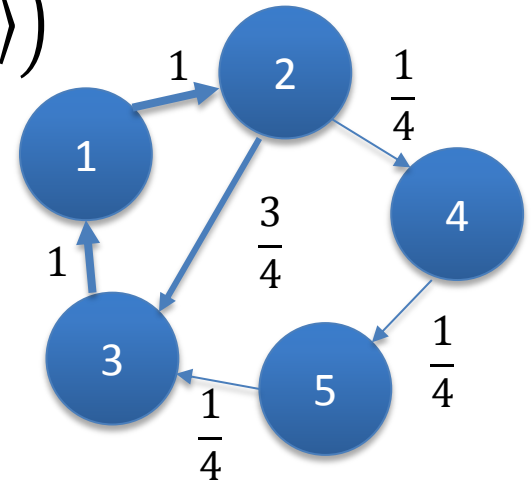


# Graph bipartiteness

$$\begin{aligned}
 |t\rangle = & \left( |0\rangle + |1_{1,0}\rangle + |1_{1,1}\rangle \right) - \left( |1_{1,0}\rangle + |2_{1,1}\rangle \right) \\
 & + \frac{3}{4} \left( |2_{1,1}\rangle + |3_{1,0}\rangle \right) \\
 & + \frac{1}{4} \left( \left( |2_{1,1}\rangle + |4_{1,0}\rangle \right) - \left( |4_{1,0}\rangle + |5_{1,1}\rangle \right) \right. \\
 & \left. + \left( |5_{1,1}\rangle + |3_{1,0}\rangle \right) \right) - \left( |3_{1,0}\rangle + |1_{1,1}\rangle \right)
 \end{aligned}$$

$$wsize_1(P, x)$$

$$\begin{aligned}
 & \leq 1^2 + (-1)^2 + \left(\frac{3}{4}\right)^2 + \left(\frac{1}{4}\right)^2 + \left(-\frac{1}{4}\right)^2 \\
 & + \frac{1}{4} + (-1)^2 = 3 + \frac{12}{16}
 \end{aligned}$$

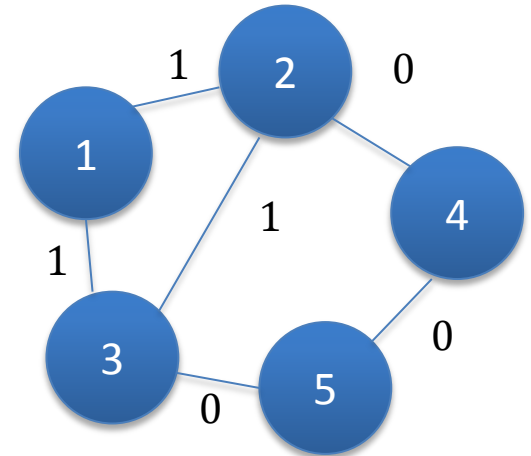


# Graph bipartiteness

$$\begin{aligned}
 |t\rangle = & \\
 & \frac{1}{3} \left( (|0\rangle + |1_{1,0}\rangle + |1_{1,1}\rangle) - (|1_{1,0}\rangle + |2_{1,1}\rangle) + (|2_{1,1}\rangle + |3_{1,0}\rangle) - (|3_{1,0}\rangle + |1_{1,1}\rangle) \right) \\
 & + \frac{1}{3} \left( (|0\rangle + |2_{2,0}\rangle + |2_{2,1}\rangle) - (|2_{2,0}\rangle + |3_{2,1}\rangle) + (|3_{2,1}\rangle + |1_{2,0}\rangle) - (|1_{2,0}\rangle + |2_{2,1}\rangle) \right) \\
 & + \frac{1}{3} \left( (|0\rangle + |3_{3,0}\rangle + |3_{3,1}\rangle) - (|3_{3,0}\rangle + |1_{3,1}\rangle) + (|1_{3,1}\rangle + |2_{3,0}\rangle) - (|2_{3,0}\rangle + |3_{3,1}\rangle) \right)
 \end{aligned}$$

$$\begin{aligned}
 wsize_1(P, x) &\leq 3 * \left(\frac{1}{3}\right)^2 * (1^2 + (-1)^2 + 1^2 + (-1)^2) \\
 &= \frac{4}{3} < 3 + \frac{12}{16}
 \end{aligned}$$

$$\mathbf{wsize_1(P) = O(1)}$$



# Graph bipartiteness: complexity

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- Need to find such  $|w'\rangle$  that  $\langle w'|0\rangle = 1$  and  $\forall |y\rangle \in V(x)$  ( $|w'\rangle \perp |y\rangle$ )
  - Must have  $\langle w'|(|0\rangle + |k_{k,0}\rangle + |k_{k,1}\rangle)\rangle = 0$
  - For every  $k$  set  $\langle w'|k_{k,0}\rangle = 0$  and  $\langle w'|k_{k,1}\rangle = -1$ 
    - For every  $u - v$  set  $\langle w'|u_{k,b}\rangle = -\langle w'|v_{k,1-b}\rangle$
  - For any given vector  $v$  value  $\langle w'|v\rangle^2 \leq 1$
  - The total number of vectors does not exceed  $n + n^3$
  - $wsize_0(P) = O(n^3)$
  - $wsize(P) = \sqrt{wsize_1(P) * wsize_0(P)} = \theta(n\sqrt{n})$
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# Graph connectivity

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- Main idea: is every vertex reachable from vertex 1?
- Target vector:  $|t\rangle = |0_2\rangle + |0_3\rangle + \dots + |0_N\rangle$
- For every  $k \in [2..n]$ : can use the free vector
$$|0_k\rangle + |1_k\rangle - |k_k\rangle$$
- For every  $k \in [2..n]$ :
  - for every edge  $u - v$  (where input  $x_{u,v} = 1$ ) make available the vector:
$$|u_k\rangle - |v_k\rangle$$
- **$wsize(P) = \theta(n\sqrt{n})$**

# Eulerian cycle

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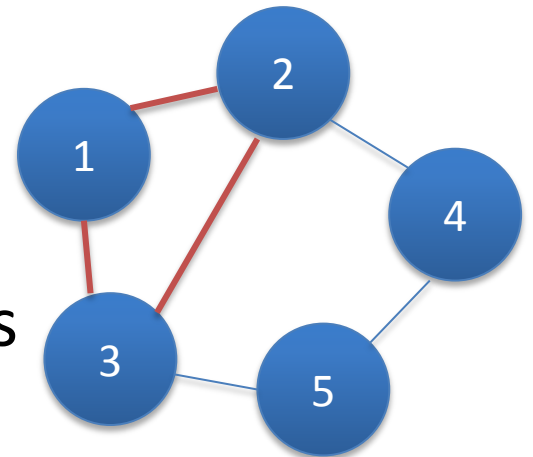
- Main idea: check for vertex with an odd degree
- Target vector:  $|t\rangle = |0\rangle$
- For every  $k \in [1..n]$  can use vectors:
  - free vector  $|0\rangle + |k_{0,0}\rangle - |k_{n,1}\rangle$
  - For every  $i \in [1..n]$ :
    - If  $(x_{k,i} = 1)$  then can use vectors:  
 $-|k_{i-1,0}\rangle + |k_{i,1}\rangle$  and  $-|k_{i-1,1}\rangle + |k_{i,0}\rangle$
    - if  $(x_{k,i} = 0)$  then can use vectors:  
 $-|k_{i-1,0}\rangle + |k_{i,0}\rangle$  and  $-|k_{i-1,1}\rangle + |k_{i,1}\rangle$



# Open problems

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- ❑ Graph collision: a graph is known beforehand but the vertex marking is not, check if two marked vertices are adjacent. Best lower bound is  $\Omega(\sqrt{n})$ .
- ❑ Triangle finding: check if in a given graph there are three vertices which are pairwise adjacent. Best lower bound is  $\Omega(n)$ .
- ❑ Perfect matching: check if can take exactly one entry with value «1» in each column and row from the graph's adjacency matrix



# THANKS FOR LISTENING. QUESTIONS?

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**END.**

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