

A logical approach to Isomorphism Testing and Constraint Satisfaction

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Outline

Logical complexity of graphs

Applications to Graph Isomorphism

Applications to Constraint Satisfaction (Graph Homomorphism)

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Logical complexity of graphs

Applications to Graph Isomorphism

Applications to Constraint Satisfaction (Graph Homomorphism)

First-order language of graph theory

Vocabulary:

$=$ equality of vertices

\sim adjacency of vertices

Syntax:

\wedge, \vee, \neg etc. Boolean connectives

\exists, \forall quantification over vertices
(no quantification over sets).

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Example

We can say that vertices x any y lie at distance no more than n :

$$\Delta_1(x, y) \stackrel{\text{def}}{=} x \sim y \vee x = y$$

$$\Delta_n(x, y) \stackrel{\text{def}}{=} \exists z_1 \dots \exists z_{n-1} \left(\Delta_1(x, z_1) \wedge \right. \\ \left. \wedge \Delta_1(z_1, z_2) \wedge \dots \wedge \Delta_1(z_{n-2}, z_{n-1}) \wedge \Delta_1(z_{n-1}, y) \right)$$

Succinctness measures of a formula Φ

Definition

The **width** $W(\Phi)$ is the number of variables used in Φ (different occurrences of the same variable are not counted).

Example

$W(\Delta_n) = n + 1$ but we can economize by recycling just three variables:

$$\begin{aligned}\Delta'_1(x, y) &\stackrel{\text{def}}{=} \Delta_1(x, y) \\ \Delta'_n(x, y) &\stackrel{\text{def}}{=} \exists z(\Delta'_1(x, z) \wedge \Delta'_{n-1}(z, y)).\end{aligned}$$

Succinctness measures of a formula Φ

Definition

The **depth** $D(\Phi)$ (or **quantifier rank**) is the maximum number of nested quantifiers in Φ .

- ▶ $\forall x(\forall y(\exists z(\dots)))$ – depth 3; $(\forall x \dots) \wedge (\forall y \dots) \wedge (\exists z \dots)$ – depth 1

Example

$D(\Delta'_n) = n - 1$ but we can economize using the halving strategy:

$$\begin{aligned}\Delta''_1(x, y) &\stackrel{\text{def}}{=} \Delta_1(x, y) \\ \Delta''_n(x, y) &\stackrel{\text{def}}{=} \exists z \left(\Delta''_{\lfloor n/2 \rfloor}(x, z) \wedge \Delta''_{\lfloor n/2 \rfloor}(z, y) \right).\end{aligned}$$

Now $D(\Delta''_n) = \lceil \log n \rceil$ and $W(\Delta''_n) = 3$.

Definition

A statement Φ defines a graph G if Φ is true on G but false on every non-isomorphic graph H .

Example

P_n , the path on n vertices, is defined by

$$\begin{aligned} & \forall x \forall y \Delta_{n-1}(x, y) \wedge \neg \forall x \forall y \Delta_{n-2}(x, y) && \% \text{ diameter} = n-1 \\ & \wedge \forall x \forall y_1 \forall y_2 \forall y_3 (x \sim y_1 \wedge x \sim y_2 \wedge x \sim y_3 \\ & \quad \rightarrow y_1 = y_2 \vee y_2 = y_3 \vee y_3 = y_1) && \% \text{ max degree} < 3 \\ & \wedge \exists x \exists y \forall z (x \sim y \wedge (z \sim x \rightarrow z = y)) && \% \text{ min degree} = 1 \end{aligned}$$

The logical depth and width of a graph

Definition

$D(G)$ is the minimum $D(\Phi)$ over all Φ defining G .

$W(G)$ is the minimum $W(\Phi)$ over all Φ defining G .

Example

- ▶ $W(P_n) \leq 4$
- ▶ $D(P_n) < \log n + 3$

Remark

$W(G) \leq D(G) \leq n + 1$, where $n = v(G)$

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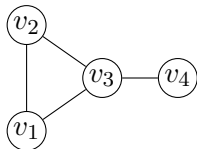
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$$\exists x_1 \exists x_2 \exists x_3 \exists x_4 \forall y$$

$$\left(\bigwedge_{1 \leq i < j \leq 4} x_i \neq x_j \wedge \bigvee_{1 \leq i \leq 4} y = x_i \wedge \right.$$

$$x_1 \sim x_2 \wedge x_1 \sim x_3 \wedge x_2 \sim x_3 \wedge x_3 \sim x_4 \wedge$$

$$\left. \wedge x_1 \not\sim x_4 \wedge x_2 \not\sim x_4 \right)_{10/100}$$

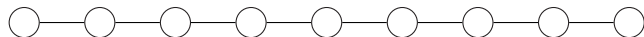
How to determine $W(G)$ or $D(G)$?

- ▶ $D(G) = \max_{H \not\cong G} D(G, H)$, where $D(G, H)$ is the minimum quantifier depth needed to distinguish between G and H . Similarly for $W(G)$.
- ▶ $D(G, H)$ and $W(G, H)$ are characterized in terms of a combinatorial game:

G and H are distinguishable with k variables and quantifier depth r iff Spoiler wins the k -pebble Ehrenfeucht game on G and H in r rounds.

The k -pebble Ehrenfeucht game

Example 1: $W(P_n, P_{n+1}) \leq 3$, $D(P_n, P_{n+1}) \leq \log_2 n + 3$



$G = P_9$



$H = P_{10}$

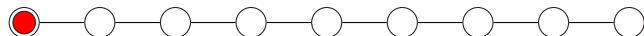
Two players: Spoiler and Duplicator



Duplicator's objective: to keep a partial isomorphism

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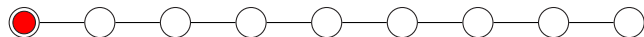
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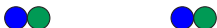


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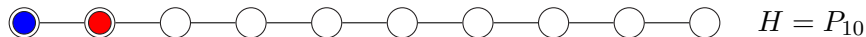
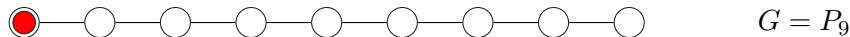
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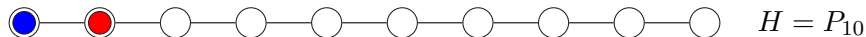
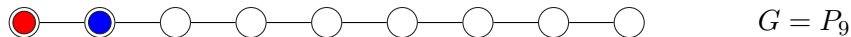
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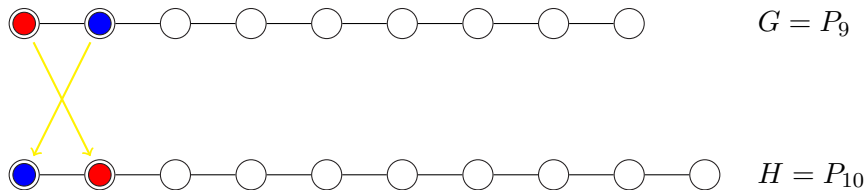
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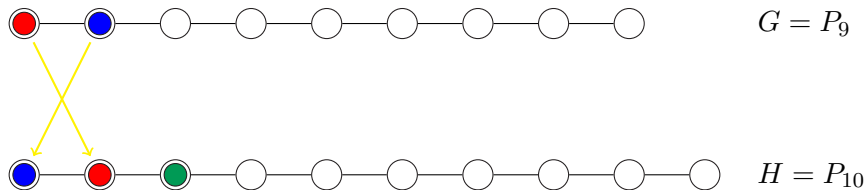
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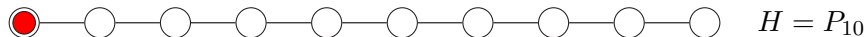
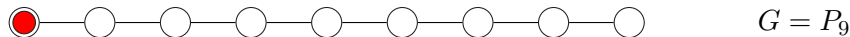
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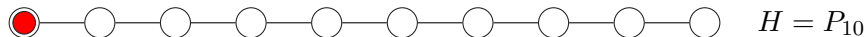
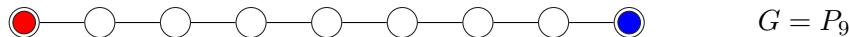
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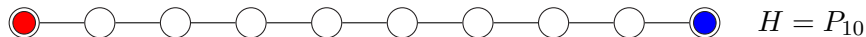
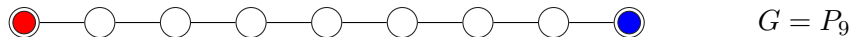
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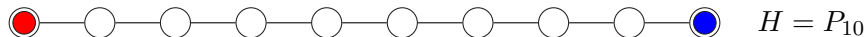
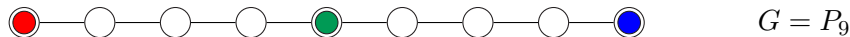
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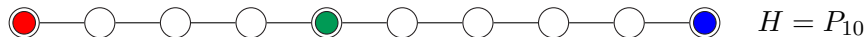
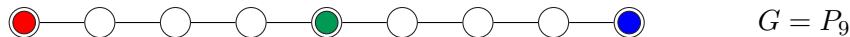
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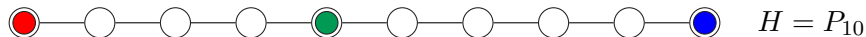
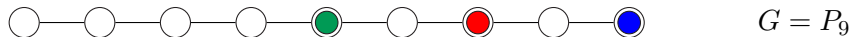


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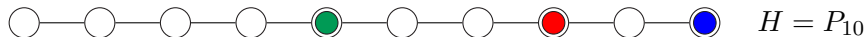
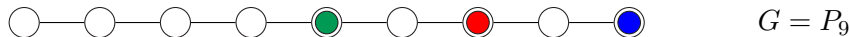


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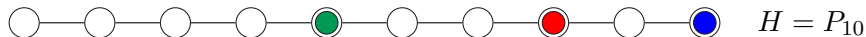


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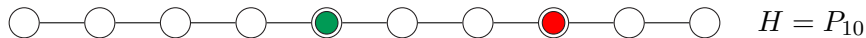


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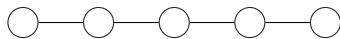


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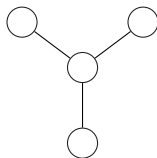
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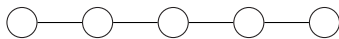
$G = P_5$



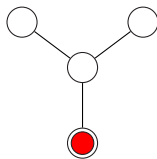
$K_{1,3}$ in H

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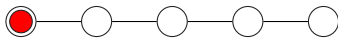
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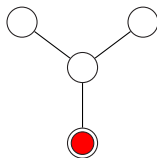
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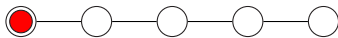
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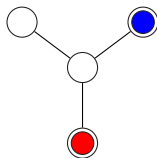
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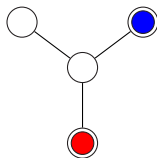
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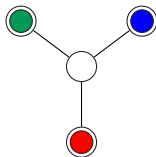
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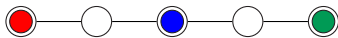
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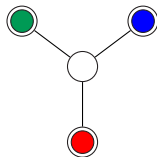
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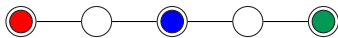
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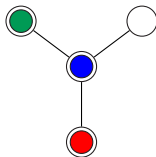
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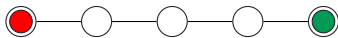
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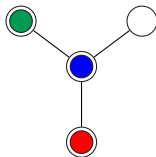
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$K_{1,3}$ in H

Left aside from this talk

Consider n -vertex graphs.

- ▶ If $G \not\cong H$, then $D(G, H) \leq n$. Can this be improved?
- ▶ What is $D(G)$ if G is chosen at random?
- ▶ What is the minimum possible value of $D(G)$?
- ▶ How do the answers change if we restrict the number of quantifier alternations?

(joint work with Joel Spencer and Oleg Pikhurko)

k -variable logic

$D^k(G)$ denotes the logical depth of G in the k -variable logic (assuming $W(G) \leq k$).

For example, $D^3(P_n) \leq \log n + 3$.

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For example, $D^3(P_n) \leq \log n + 3$.

A disturbing fact: We may need many variables even for very simple graphs.

For example, $W(K_{1,n}) \geq n$ because $W(K_{1,n}, K_{1,n+1}) \geq n$.

Logic with counting quantifiers

$\exists^m x \Psi(x)$ means that there are at least m vertices x having property Ψ .

The counting quantifier \exists^m contributes 1 in the quantifier depth whatever m .

Example

$K_{1,n}$ can now be defined by

$$\begin{aligned} \exists^{n+1}(x = x) \wedge \neg \exists^{n+2}(x = x) \wedge \\ \exists x \forall y \forall z (y \neq x \wedge z \neq x \rightarrow y \sim x \wedge y \not\sim z) \end{aligned}$$

Therefore, $W_{\#}(K_{1,n}) \leq 3$ and $D_{\#}^3(K_{1,n}) \leq 3$.

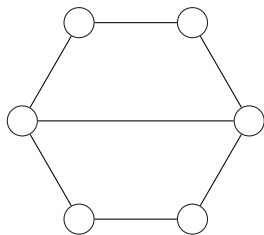
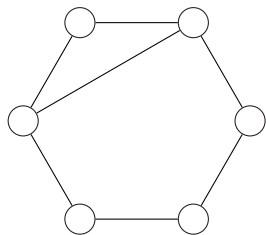
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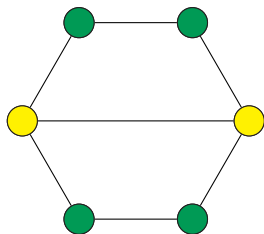
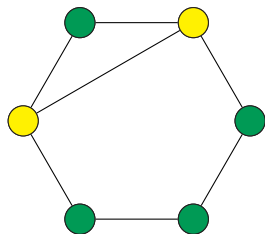
Applications to Constraint Satisfaction (Graph Homomorphism)

Color refinement algorithm



Initial coloring is monochromatic.

Color refinement algorithm

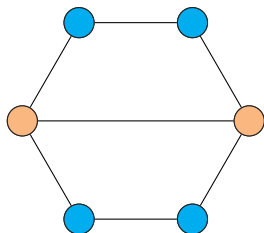
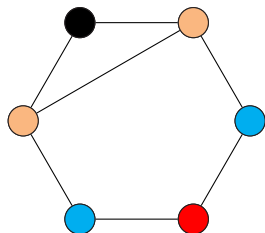


New color of a vertex = old color + old colors of all neighbours.

$$\bullet = \{\circ, \{\circ, \circ\}\}$$

$$\bullet = \{\circ, \{\circ, \circ, \circ\}\}$$

Color refinement algorithm



Next refinement.

● = {●, {●, ●}} (absent in the second graph)

● = {●, {●, ●}} (absent in the second graph)

● = {●, {●, ●}}

● = {●, {●, ●, ●}}

Color refinement algorithm

Theorem (Immerman, Lander 90)

Color Refinement works correctly on G and every H iff $W_{\#}(G) \leq 2$.

This is the case for

▶ all trees

[Edmonds 65]

▶ almost all graphs

[Babai, Erdős, Selkow 82]

k -dimensional Weisfeiler-Lehman algorithm

- ▶ 1-dim WL = the color refinement algorithm
- ▶ k -dim WL colors $V(G)^k$
- ▶ Initial coloring: $C^1(\bar{u}) =$ the equality type of $\bar{u} \in V(G)^k$ and the isomorphism type of the spanned subgraph
- ▶ Color refinement:
$$C^i(\bar{u}) = \{C^{i-1}(\bar{u}), \{(C^{i-1}(\bar{u}^{1,x}), \dots, C^{i-1}(\bar{u}^{k,x}))\}_{x \in V}\},$$
where $(u_1, \dots, u_i, \dots, u_k)^{i,x} = (u_1, \dots, x, \dots, u_k)$

The Weisfeiler-Lehman algorithm

- ▶ purports to decide if input graphs G and H are isomorphic:
 - ▶ If $G \cong H$, the output is correct,
 - ▶ if $G \not\cong H$, the output can be wrong;
- ▶ has two parameters: **dimension** and **number of rounds**.
- ▶ Fixed dimension $k \implies \leq n^k$ rounds \implies polynomial running time.
- ▶ Fixed dimension and $O(\log n)$ rounds \implies parallel logarithmic time.

Theorem (Cai, Fürer, Immerman 92)

The r -round k -dim WL works correctly on G and every H if

$$k = W_{\#}(G) - 1 \text{ and } r = D_{\#}^{k+1}(G) - 1.$$

On the other hand, it is wrong on (G, H) for some H if

$$k < W_{\#}(G) - 1, \text{ whatever } r.$$

The Weisfeiler-Lehman algorithm

Corollary (Cai, Fürer, Immerman 92)

Let \mathcal{C} be a class of graphs G with $W_{\#}(G) \leq k$ for a constant k .
Then Graph Isomorphism for \mathcal{C} is solvable in P .

Corollary (Grohe, V. 06)

1. Let \mathcal{C} be a class of graphs G with $D_{\#}^k(G) = O(\log n)$.
Then Graph Isomorphism for \mathcal{C} is solvable in $\text{TC}^1 \subseteq \text{NC}^2 \subseteq \text{AC}^2$.
2. Let \mathcal{C} be a class of graphs G with $D^k(G) = O(\log n)$.
Then Graph Isomorphism for \mathcal{C} is solvable in $\text{AC}^1 \subseteq \text{TC}^1$.

Classes of graphs: Trees

- ▶ $W_{\#}(T) \leq 2$ for every tree T .
- ▶ $D_{\#}^2(P_n) \geq \frac{n}{2} - 1$
- ▶ one extra variable \implies logarithmic depth !

Theorem

If T is a tree on n vertices, then $D_{\#}^3(T) \leq 3 \log n + 2$.

Isomorphism of trees (history revision)

Theorem

If T is a tree on n vertices, then $D_{\#}^3(T) \leq 3 \log n + 2$.

Testing isomorphism of trees is

- ▶ in Log-Space [Lindell 92]
- ▶ in AC^1 [Miller-Reif 91]
- ▶ in AC^1 if $\Delta = O(\log n)$ [Ruzzo 81]
- ▶ in Lin-Time by 1-WL ($W_{\#}(T) = 2$) [Edmonds 65]

Miller and Reif [SIAM J. Comput. 91]: “No polylogarithmic parallel algorithm was previously known for isomorphism of unbounded-degree trees.”

However, the $3 \log n$ -round 2-WL solves it in TC^1 and is known since 68 !

Classes of graphs: Bounded tree-width, planar, interval

Theorem

For a graph G of tree-width k on n vertices

$$W_{\#}(G) \leq k + 2 \quad [\text{Grohe, Mariño 99}];$$

$$D_{\#}^{4k+4}(G) < 2(k + 1) \log n + 8k + 9 \quad [\text{Grohe, V. 06}].$$

Theorem

For a planar graph G on n vertices

$$W_{\#}(G) = O(1) \quad [\text{Grohe 98}].$$

If G is, moreover, 3-connected, then

$$D^{15}(G) < 11 \log n + 45 \quad [\text{V. 07}].$$

Theorem

For an interval graph G on n vertices

$$W_{\#}(G) \leq 3 \quad [\text{Evdokimov et al. 00, Laubner 10}];$$

$$D_{\#}^{15}(G) < 9 \log n + 8 \quad [\text{Köbler, Kuhnert, Laubner, V. 11}].$$

Graphs with an excluded minor

Theorem (Grohe 11)

For each F , if G excludes F as a minor, then

$$W_{\#}(G) = O(1).$$

Open problem

Is it then true that $D_{\#}^k(G) = O(\log n)$ for some constant k ?

Outline

Logical complexity of graphs

Applications to Graph Isomorphism

Applications to Constraint Satisfaction (Graph Homomorphism)

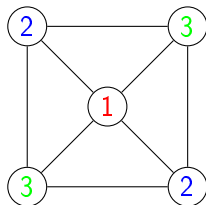
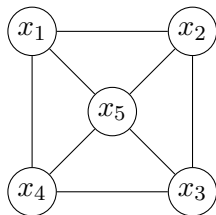
Constraint Satisfaction Problem (CSP)

Variables x_1, x_2, x_3, x_4, x_5

Values $x_i \in \{1, 2, 3\}$

Constraints $x_1 \neq x_2, x_2 \neq x_3, x_3 \neq x_4, x_4 \neq x_1,$
 $x_1 \neq x_5, x_2 \neq x_5, x_3 \neq x_5, x_4 \neq x_5$

Question: Is there an assignment of values to the variables satisfying all constraints?



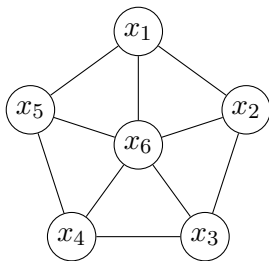
Constraint Satisfaction Problem (CSP)

Variables $x_1, x_2, x_3, x_4, x_5, x_6$

Values $x_i \in \{1, 2, 3\}$

Constraints $x_1 \neq x_2, x_2 \neq x_3, x_3 \neq x_4, x_4 \neq x_5, x_5 \neq x_1,$
 $x_1 \neq x_6, x_2 \neq x_6, x_3 \neq x_6, x_4 \neq x_6, x_5 \neq x_6$

Question: Is there an assignment of values to the variables satisfying all constraints?



No!

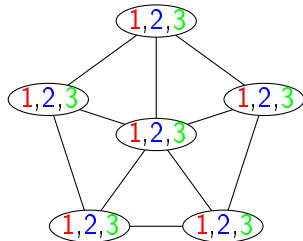
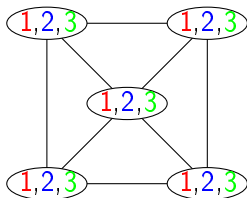
Constraint propagation

Methodology: derivation instead of search

Example: 3-COLORABILITY.

We can choose an arbitrary edge and color it arbitrarily.

Derivation rules: $\frac{x = 1, y \neq x}{y \neq 1}$ etc.



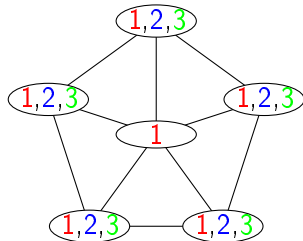
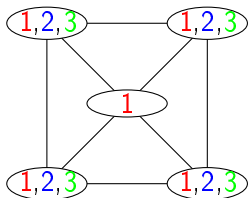
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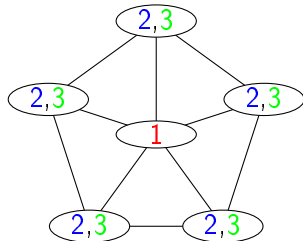
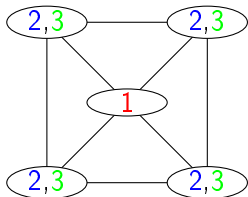
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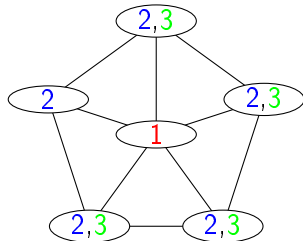
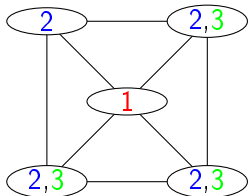
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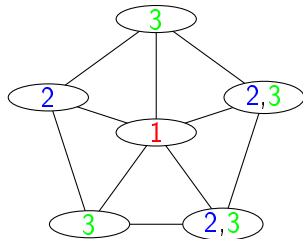
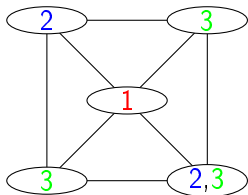
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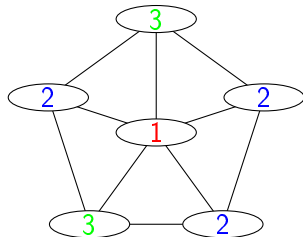
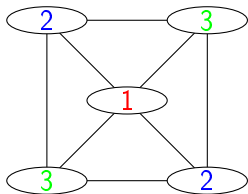
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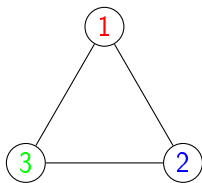
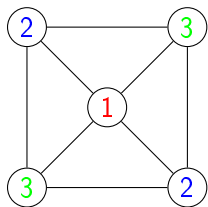
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Derivation rules: $\frac{x = 1, y \neq x}{y \neq 1}$ etc.



The Feder-Vardi paradigm: a CSP = a Homomorphism Problem

For example, a graph G is 3-colorable iff there is a homomorphism from G to K_3 (notation: $G \rightarrow K_3$).



A logic and a game for the Homomorphism Problem

The following three conditions are equivalent:

- ▶ $G \not\cong H$,
- ▶ some **existential-positive** formula distinguishes G from H ,
- ▶ Spoiler has a winning strategy in the existential k -pebble game on G and H for some k .

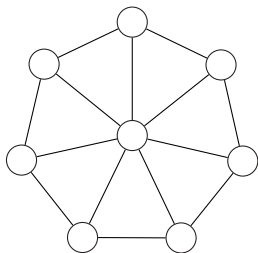
The **existential k -pebble game** on G and H is the version of the k -pebble Ehrenfeucht game where

- ▶ Spoiler moves **always in G** ,
- ▶ Duplicator must keep a partial **homomorphism**.

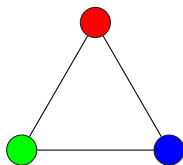
An example

Let G_n denote the wheel graph with n vertices.

If n is even, then Spoiler wins the existential game on G_n and K_3 with 4 pebbles.



Spoiler



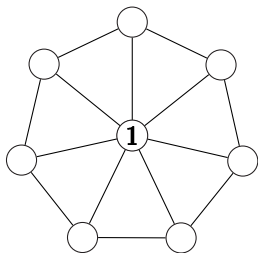
Duplicator



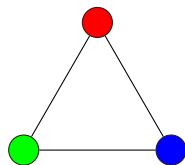
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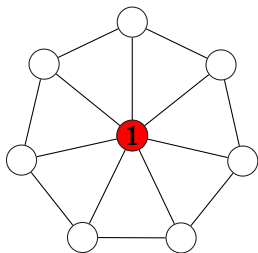
Duplicator



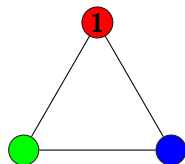
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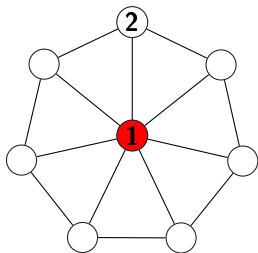
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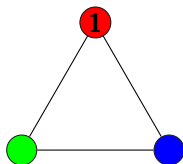
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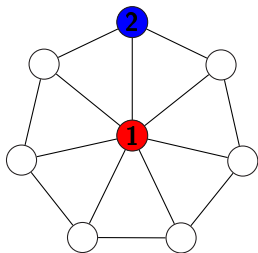
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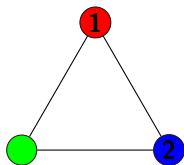
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Spoiler

③ ④



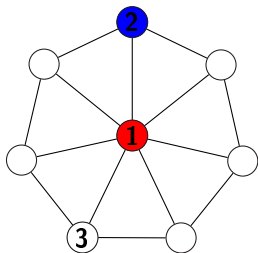
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An example

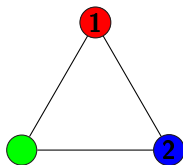
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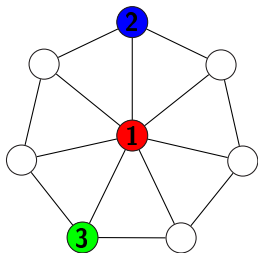
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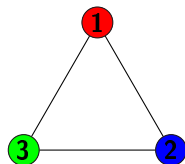
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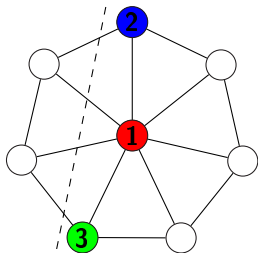
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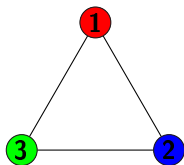
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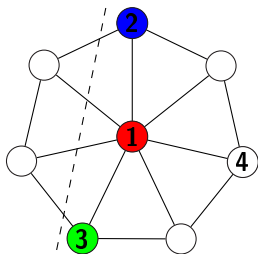
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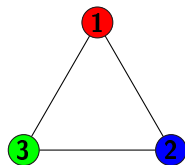
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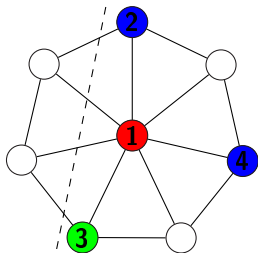
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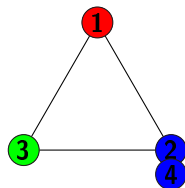
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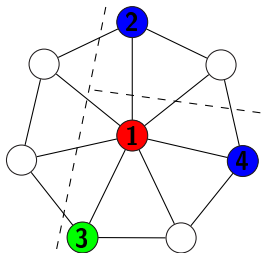


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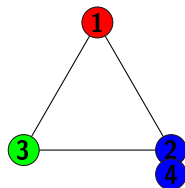
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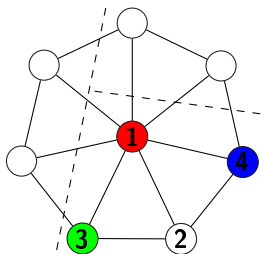


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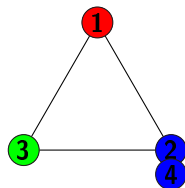
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Spoiler



Duplicator

The triad: A logic, a game, an algorithm

Theorem (Kolaitis, Vardi 95)

Suppose that $G \not\equiv H$. The the following three conditions are equivalent:

- ▶ $W_{\exists,+}(G, H) \leq k$, i.e., G is distinguishable from H by an existential-positive sentence with k variables;
- ▶ Spoiler wins the existential k -pebble game on G and H ;
- ▶ k -Consistency Checking recognizes that $G \not\equiv H$.

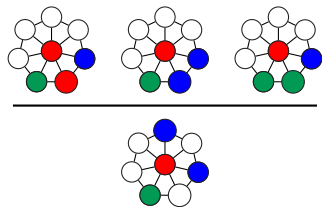
k -Consistency Checking (recasted)

Algorithmic problem

Given two finite structures G and H , does Spoiler win the existential k -pebble game on these structures?

- ▶ This is a relaxation of the homomorphism problem.
- ▶ For small k , it is commonly used as a heuristics approach.

A **propagation-based algorithm** makes derivations like



- winning positions for Spoiler



- a winning position too

(a position is a mapping of $\leq k$ vertices from $V(G)$ into $V(H)$)

Spoiler has a winning strategy \Leftrightarrow the uncolored graph is derivable. Since there are at most $N = v(G)^k v(H)^k$ positions, all derivations can be generated in time N^{k+1} (the wasteful version of k -consistency checking). If k is fixed, this takes polynomial time.

The time complexity of k -Consistency Checking

Theorem

The k -Consistency problem is solvable in

- ▶ *time $O(v(G)^k v(H)^k) = O(n^{2k})$ for each k [Cooper 89]*
- ▶ *but not in time $O(n^{\frac{k-3}{12}})$ for $k \geq 15$ [Berkholz 12]*

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Question. What about arc consistency ($k = 2$)?

Remark. If $k = 2$, we consider directed graphs.

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Question. What about arc consistency ($k = 2$)?

Remark. If $k = 2$, we consider directed graphs.

In practice: All arc consistency ($k = 2$) algorithms

- ▶ such as AC-1, AC-3, AC-3.1 / AC-2001, AC-3.2, AC-3.3, AC-3_d, AC-4, AC-5, AC-6, AC-7, AC-8, AC-*
- ▶ and several parallel/distributed variants

are based on constraint propagation.

Bounds for the propagation approach

Upper bounds for Arc Consistency

- ▶ Sequential: $O(v(G)e(H) + e(G)v(H))$, which implies $O(n^3)$.
- ▶ Parallel: $O(\text{depth}(G, H)) \leq O(v(G)v(H))$, implies $O(n^2)$.

Theorem (Berkholz, V. 13)

Any sequential propagation-based arc consistency algorithm takes time $\Omega(n^3)$, and any such parallel algorithm takes time $\Omega(n^2)$.

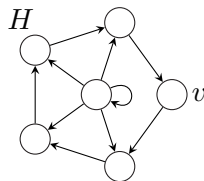
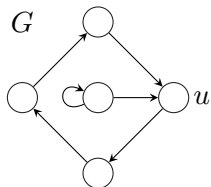
The core of the proof

Lemma

There are directed graphs G and H with $v(G) = v(H) - 1 = n$ such that

- ▶ Spoiler wins the existential 2-pebble game on G and H ;
- ▶ Duplicator can resist $\Omega(n^2)$ rounds.

Remark. $n^2 + 1$ rounds always suffice for Spoiler.



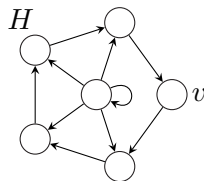
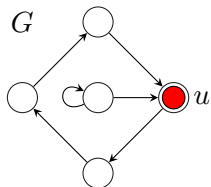
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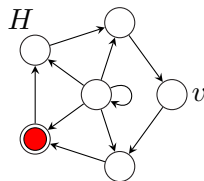
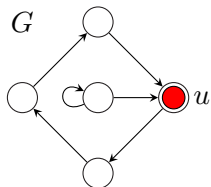
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Lemma

There are directed graphs G and H with $v(G) = v(H) - 1 = n$ such that

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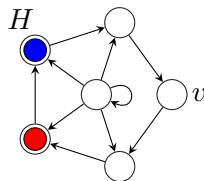
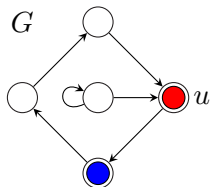
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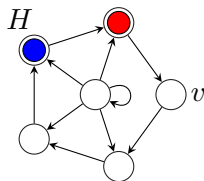
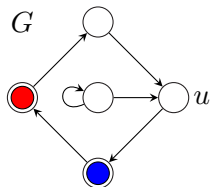
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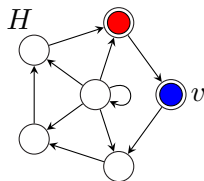
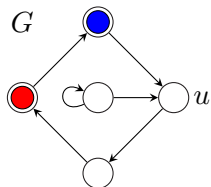
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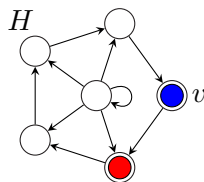
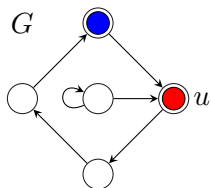
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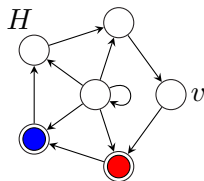
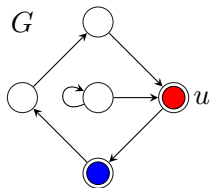
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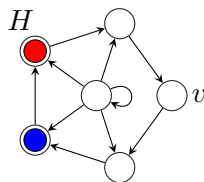
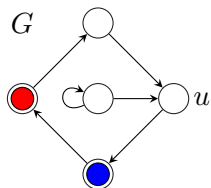
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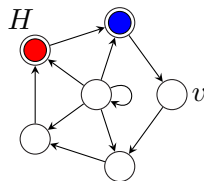
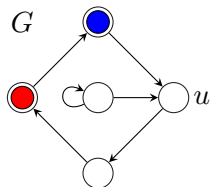
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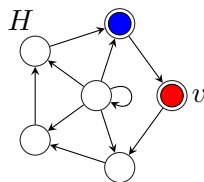
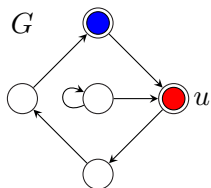
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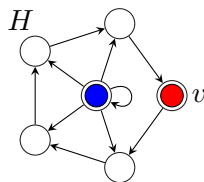
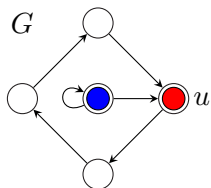
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The 3-COLORABILITY problem

Given: a graph G

Decide: $\chi(G) \leq 3$?

Solvable: in time $O(1.3289^n)$ (Beigel-Eppstein 05)

not in time $2^{o(n)}$, under the Exponential Time Hypothesis

A reminder: The non-3-colorability of wheel graphs with even number of vertices can be established by k -consistency checking with $k = 4$.

Question. What is the minimum $k = k(n)$ such that k -consistency checking is successful for all graphs with n -vertices?

Dynamic width of the 3-colorability problem

Definition

$$W(n) = \{W_{\exists,+}(G, K_3) : v(G) = n, \chi(G) > 3\}$$

Remark

- ▶ If $W(n) \leq k(n)$, then 3COL is solvable in time $n^{O(k(n))}$.
- ▶ $\text{NP} \neq \text{P} \Rightarrow W(n)$ is unbounded.

Theorem (Nešetřil, Zhu 96)

$$W(n) = \Omega\left(\frac{\log \log n}{\log \log \log n}\right).$$

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Remark

- ▶ Exponential Time Hypothesis $\implies W(n) = \Omega(n/\log n)$.

Theorem (Atserias, Dawar, V. 14)

$$W(n) = \Omega(n).$$

Dynamic width of 3COL over planar graphs

3COL of planar graphs is NP-complete, solvable in time $2^{O(\sqrt{n})}$ but, under Exponential Time Hypothesis, not in time $2^{o(\sqrt{n})}$ (Marx 13).

Definition

$$W_{\text{planar}}(n) = \max \{ W_{\exists,+}(G, K_3) : G \text{ planar, } v(G) = n, \chi(G) > 3 \}.$$

Remark

- ▶ $W_{\text{planar}}(n) \leq 5\sqrt{n}$ because $tw(G) \leq 5\sqrt{n} - 1$ for planar G , which allows Spoiler to use a divide-and-conquer strategy like for the wheel graphs.
- ▶ Exponential Time Hypothesis $\Rightarrow W_{\text{planar}}(n) = \Omega(\sqrt{n}/\log n)$.

Theorem (Atserias, Dawar, V. 14)

$$W_{\text{planar}}(n) = \Omega(\sqrt{n}).$$

Conclusion

Our lower bounds show that Consistency Checking is not an optimal approach to get an exact exponential algorithm for 3-COLORABILITY, also when only planar inputs are considered.

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Thank you for your attention!