# Quantum Speedups for Exponential-Time Dynamic Programming Algorithms

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#### Quantum algorithms for NP-hard problems

 Algorithms for many NP-hard problems are widely used despite the exponential running time.

Can we speed these algorithms up using quantum computation?

#### Example: the travelling salesman problem

• We are given a graph G(V, E) of *n* cities, with edge weights denoting the travel time between each pair.



#### Example: the travelling salesman problem

 A travelling salesman wants to visit every city exactly once and return back to his starting position as fast as possible.



• Classically can be solved in  $O^*(2^n)$ .

#### Grover's search

• A quantum algorithm to find an answer from *n* independent procedures, each taking some time *T*, in time  $O(T\sqrt{n})$ .

SAT over n variables is believed to not be solvable faster than O<sup>\*</sup>(2<sup>n</sup>) classically.

Grover's search over all  $2^n$  possible assignments gives an  $O^*(\sqrt{2^n})$  quantum algorithm.

Can we achieve a similar quadratic improvement for other NP-hard problems?

#### The naive algorithm for the TSP

Try every possible order of cities.

■ There are (n − 1)! possible orders, checking the length of a path takes O(n) time.

This gives a total complexity of

$$O(n \cdot (n-1)!) = O(n!).$$

#### Quantum version of the naive algorithm

Perform Grover's search over every possible order of cities.

• This gives a quadratic improvement:

$$O\left(\sqrt{n!}\right).$$

• A DP algorithm solving the TSP in  $O^*(2^n)$  time.

■ For each subset S ⊆ V and pair start, end ∈ S, compute the shortest distance D(S, start, end) from start visiting every city in S and ending in end.

### Bellman-Held-Karp Algorithm dynamic programming

• 
$$D(\{v\}, v, v) = 0.$$

$$\square D(S, start, end) = \min_{prev \in S \atop prev \neq end} \{D(S \setminus \{end\}, start, prev) + w(prev, end)\}.$$

• Answer:  $\min_{\text{start,end} \in V} \{D(V, \text{start, end}) + w(\text{end}, \text{start})\}.$ 

#### Bellman-Held-Karp algorithm complexity

• There are  $2^n$  subsets.

• Each subset has at most *n* choices of *start*, *prev*, *end*.

This gives a complexity of

$$O(n^3 \cdot 2^n) = O^*(2^n).$$

#### Quantum algorithm outline

• Precompute D(S, start, end) for small sets S.

 Use Grover's search to find the optimal way to to combine these small paths into a cycle.

#### Classical precomputation

■ Computing D(S, start, end) for every S : |S| ≤ t · n and every start, end takes time

$$O^*\left(\sum_{k=0}^{k=t\cdot n} \binom{n}{k}\right) = O^*\left(2^{H(t)n}\right)$$

where H is the binary entropy function.

 Our algorithm starts by doing this for sets of size up to 0.24n, with a time complexity of

$$O^*(2^{H(0.24)n}) \approx O^*(1.73^n).$$

#### City set splits

- We can split the set into halves of size n/2 in  $\binom{n}{n/2}$  ways.
- For each split, also choose the start and end vertices, giving only an  $n^4$  factor.





Now we find paths in each half separately.

• We can split these further into parts of size n/4.

■ Finally, we split those into parts of size 0.24*n* and 0.01*n*, where we have already computed the optimal paths.

#### Quantum search over splits

Classically searching over these splits takes time

$$O^*\left(\binom{n}{n/2}\binom{n/2}{n/4}\binom{n/4}{0.24n}\right).$$

Grover's search takes time

$$O^*\left(\sqrt{\binom{n}{n/2}\binom{n/2}{n/4}\binom{n/4}{0.24n}}\right)\approx O^*(1.73^n).$$

#### Overall complexity

the value 0.24 balances the O<sup>\*</sup> complexity of the classical precompution and the quantum search.

This gives an O<sup>\*</sup>(1.73<sup>n</sup>) quantum algorithm for the TSP, an improvement over the O<sup>\*</sup>(2<sup>n</sup>) classical one.

#### Generalization

This algorithm works for optimization problems OPT with the following property:

$$\mathsf{OPT}(S) = \min_{\substack{T \subseteq S \\ |T| = k}} \{\mathsf{OPT}(T) + \mathsf{OPT}(S \setminus T) + f(S, T)\}.$$

■ This includes FEEDBACK ARC SET and, with some modifications, MINIMUM SET COVER.

## BHK algorithm generalization

The Bellman-Held-Karp algorithm does not require such splits.

• For it a weaker property is sufficient:

$$OPT(S) = \min_{v \in S} \{OPT(S \setminus \{v\}) + f(S, v)\}.$$

#### Path in the Hypercube



- Boolean hypercube  $\{0,1\}^n$ , edges  $x \to y$  if |x| + 1 = |y|.
- Input: a subgraph G.
- Output: is there a path from  $0^n$  to  $1^n$  in G?

#### Layers



 Select a constant number of layers with a fixed Hamming weight.

#### Classical precomputation



- Classically precompute which vertices are reachable from 0<sup>n</sup> up to the first layer.
- Symmetrically find paths from the last layer to  $1^n$ .

#### Quantum Search



- To find whether a vertex x in a further layer is reachable, perform Grover's search over vertices of the previous layer.
- Find each such vertex y, find a path between y and x recursively.

#### **Overall Complexity**



- Perform Grover's search to find a vertex x in the middle layer reachable from both sides.
- The overall complexity is  $O^*(1.817^n)$ .

#### Applications

- Vertex ordering problems: TREEWIDTH\*, MINIMUM FILL-IN\*, PATHWIDTH, SUM CUT, MINIMUM INTERVAL GRAPH COMPLETION, CUTWIDTH and OPTIMAL LINEAR ARRANGEMENT.
- With modifications to take advantage of knowing the number of edges in G, GRAPH BANDWIDTH.

# Summary

	Classical (best known)	Quantum (this work)
Travelling Salesman Problem	$O(n^2 2^n)$	$O^*(1.728^n)$
Feedback Arc Set	$O^{*}(2^{n})$	$O^{*}(1.728^{n})$
Minimum Set Cover	$O(nm2^n)$	$O(poly(m, n)1.728^{n})$
Path in the Hypercube	$O(n2^n)$	$O^{*}(1.817^{n})$
Vertex Ordering Problems	$O^{*}(2^{n})$	$O^{*}(1.817^{n})$
Graph Bandwidth	O*(4.383 <sup>n</sup> )	$O^{*}(2.946^{n})$

#### Open questions

- Quadratic speedup?
- Lower bounds?
- Subexponential memory?

# Thank you!